Evolutionary Testing of Autonomous Software Agents

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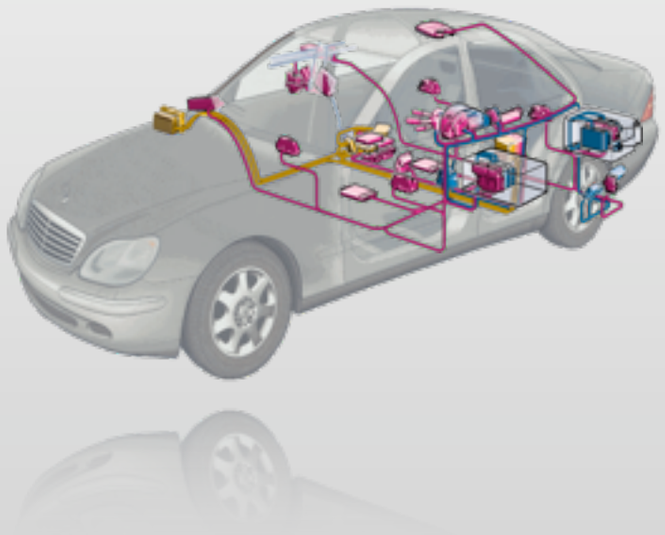
Outline

- Introduction
- Approaches
- Experiment and result discussion
- Conclusion

Introduction

Autonomous software agents are increasingly used



Testing to build confidence in their operations is crucial !

Introduction

Agent autonomy makes testing harder

- Agents make decisions for themselves based on their goals, intentions, and beliefs
- Can behave differently in response to the same input

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Testing requires:
- adequate output evaluations
- techniques that produce wide range of contexts & can search for the most demanding test cases

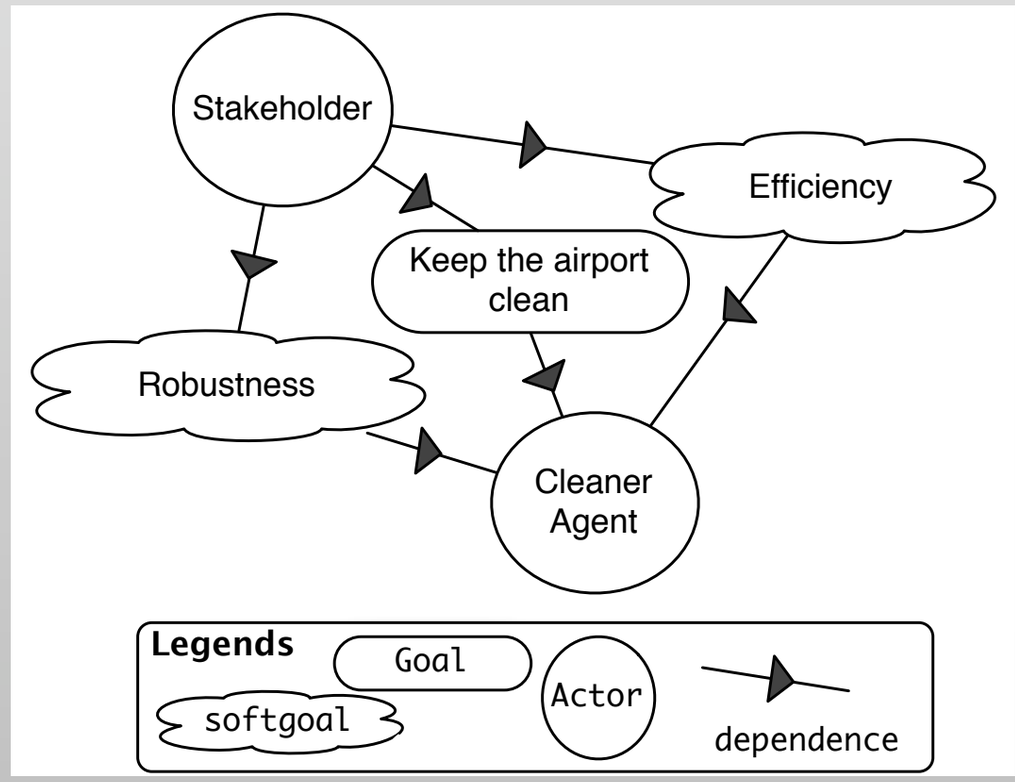
Autonomous agents operate in an open environment with high variety of situations

Background

- Testing is to find faults
- We focus on agent level
- We evaluate the exhibited performance of autonomous agents, not the underlying autonomy mechanism

Our approach (1)

Use stakeholder' requirements related to quality (e.g. efficiency) to judge autonomous agents.



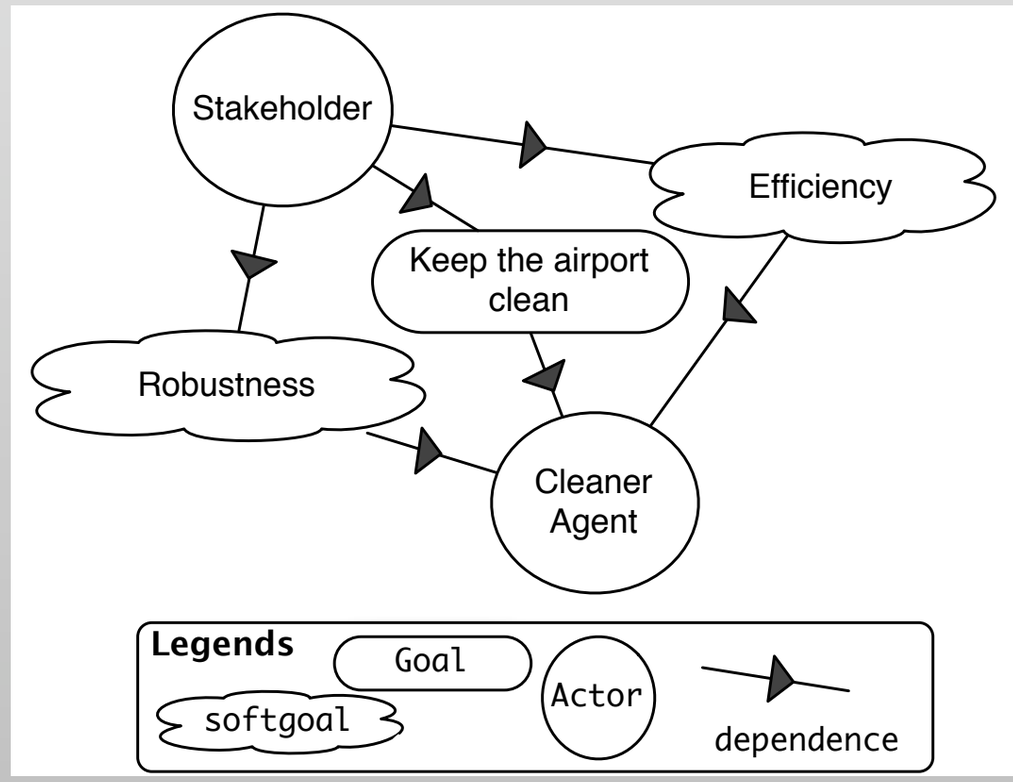
Our approach (1)

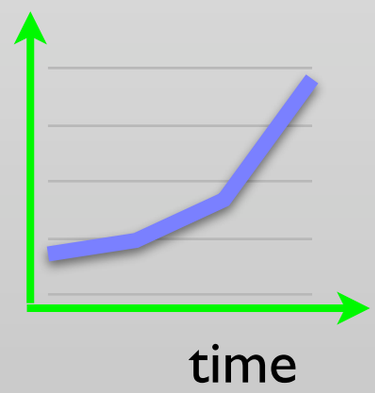
Use stakeholder' requirements related to quality (e.g. efficiency) to judge autonomous agents.

Represent these requirements as quality functions

Assess the agents under test

Drive the evolutionary generation





Our approach (2)

Use quality functions in fitness measures to drive the evolutionary generation

- Fitness of a test case tells how good the test case is
- Evolutionary testing searches for test cases having the best fitness values.

Fitness example: distance to be crashed

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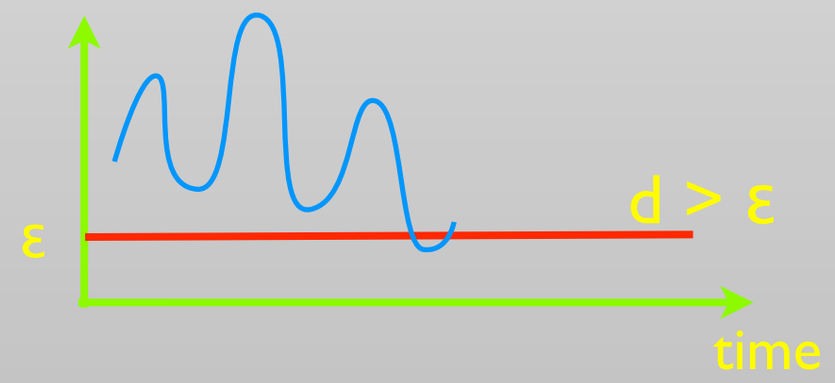
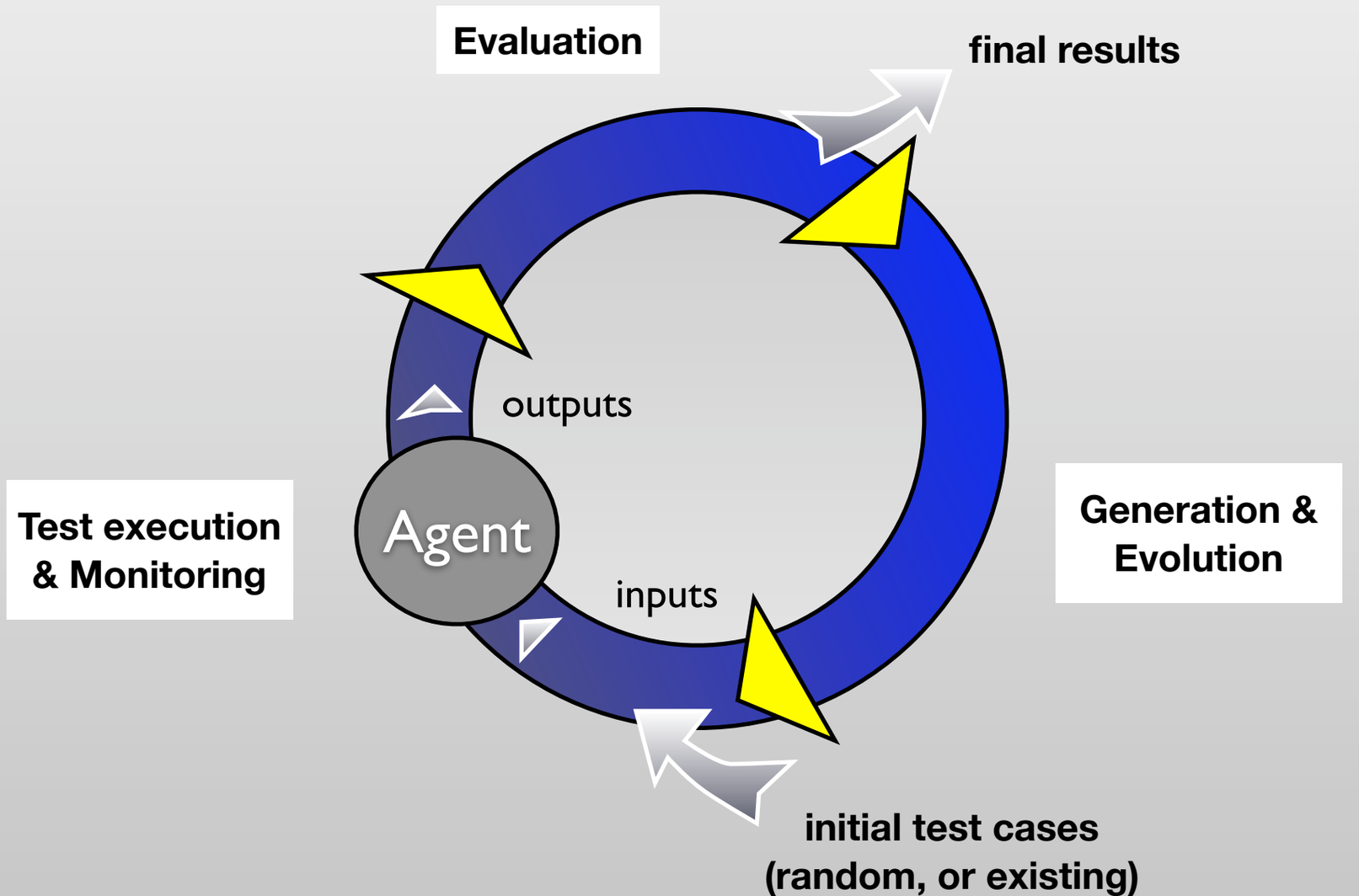


Our approach (3)

Use statistical methods to measure test case fitness

- Test outputs of a test case can be different
- A test case execution is repeated a number of times (or in parallel)
- Statistical output data are used to calculate the fitness

Evolutionary procedure



Experiments

Autonomous cleaning agent

- explore locations of important objects
- look for waste and bring them to the closest bin
- maintain battery charge
- avoid obstacles by changing course when necessary
- find the shortest path to reach a specific location
- stop when no movement is possible or running out of battery

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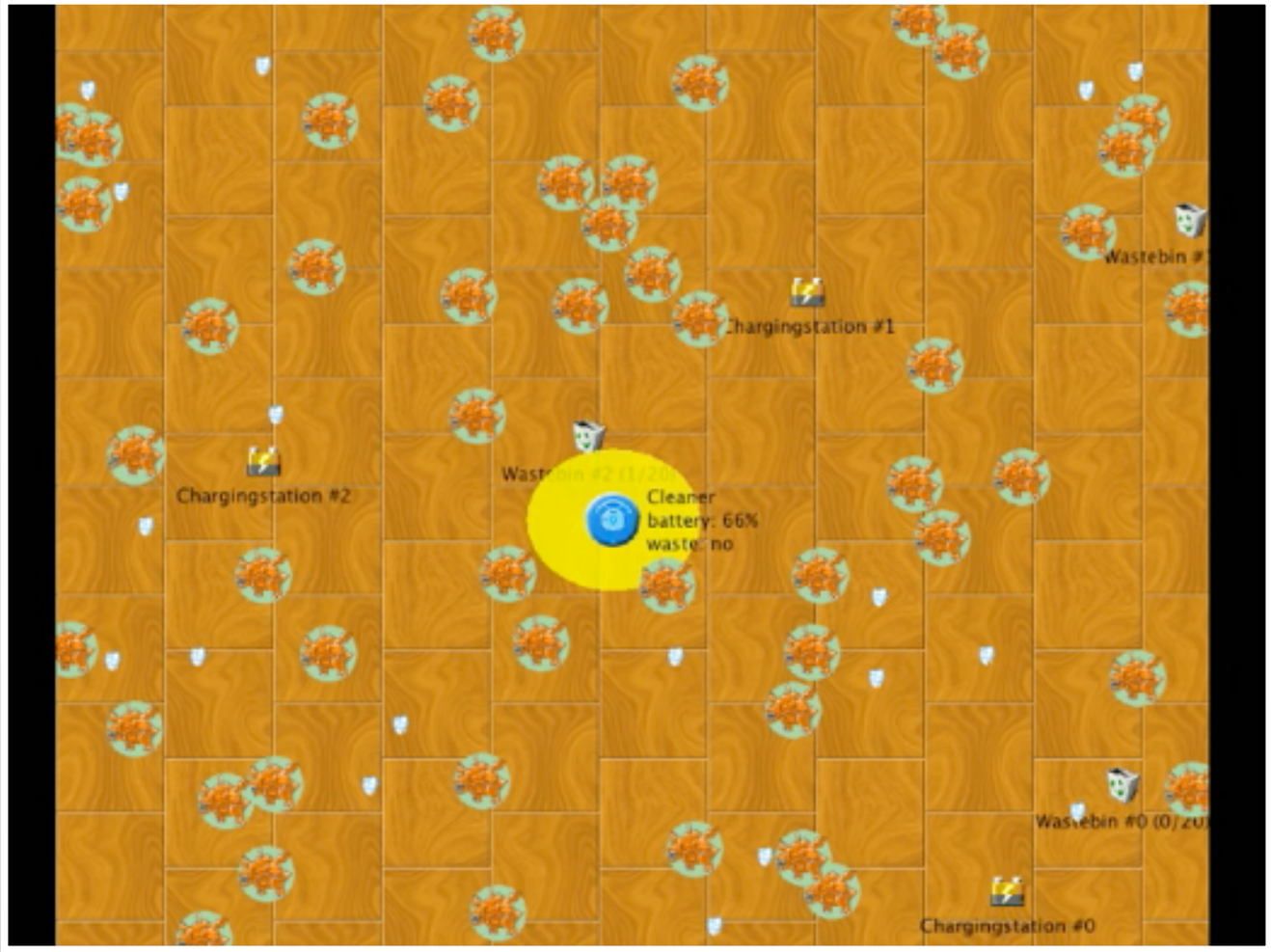
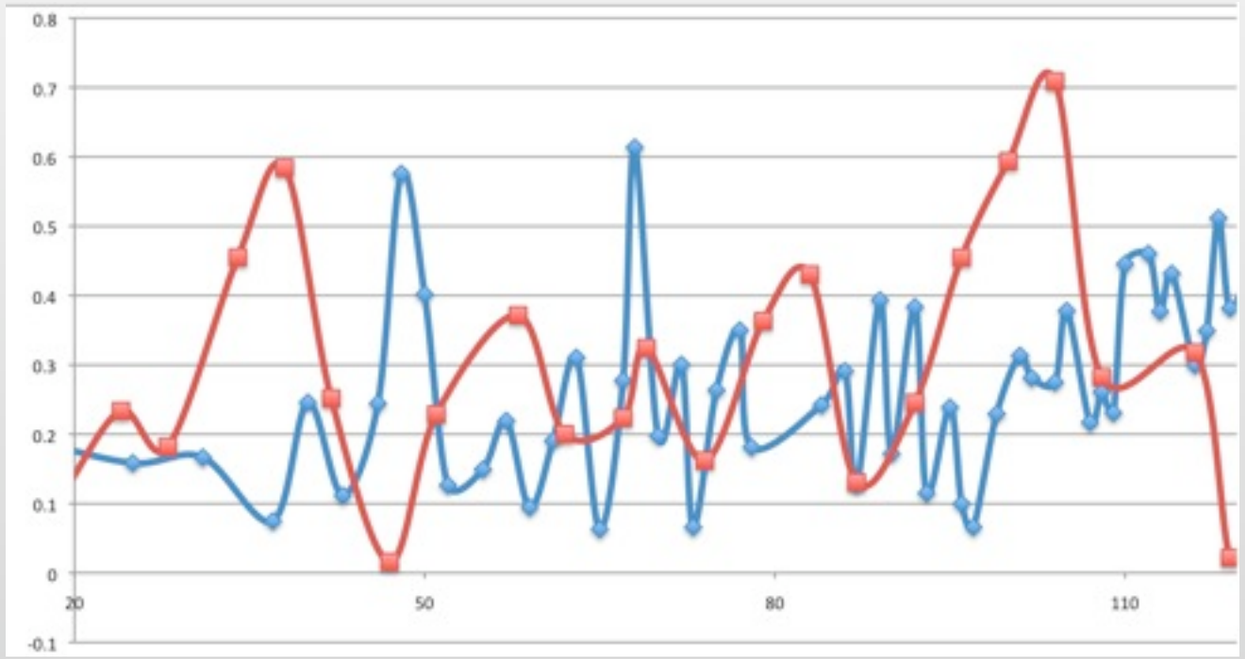


Fitness measurement

Same input environment, different outputs



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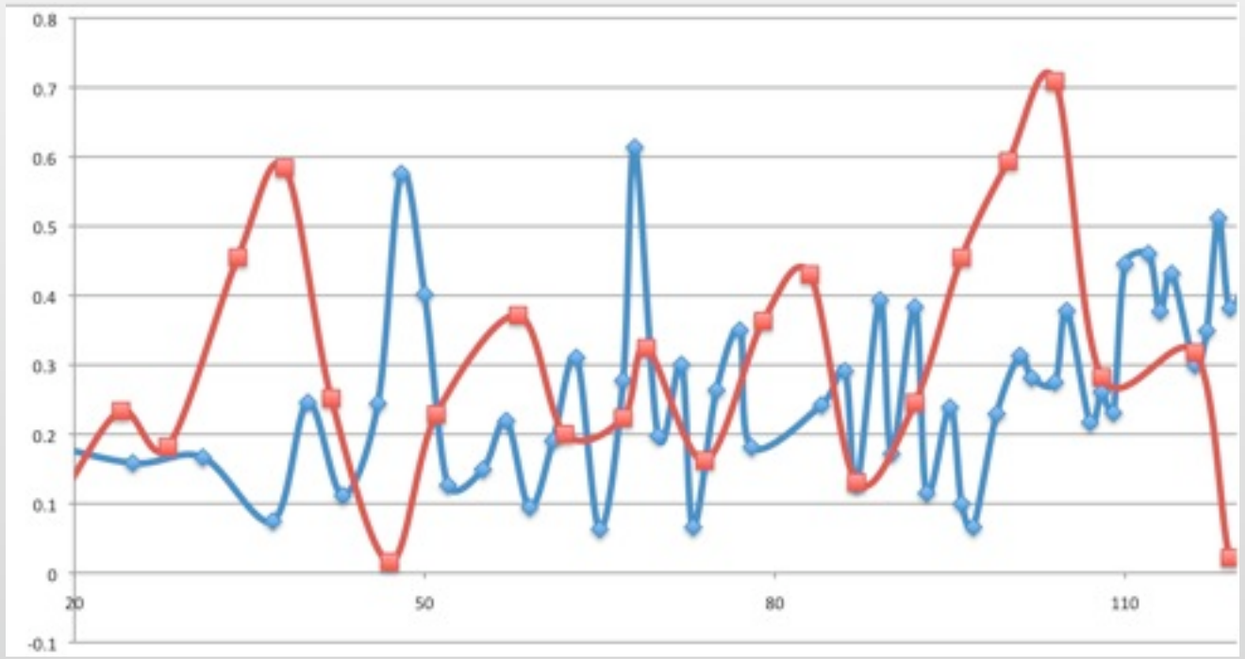
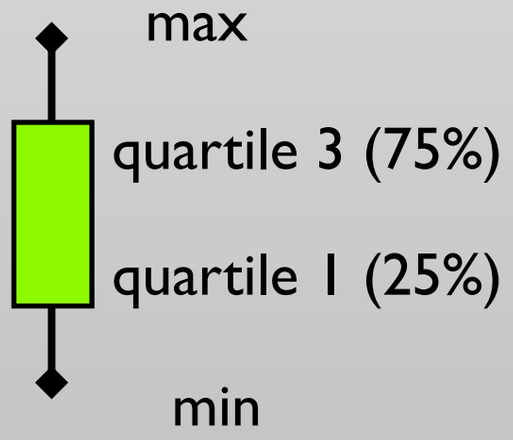
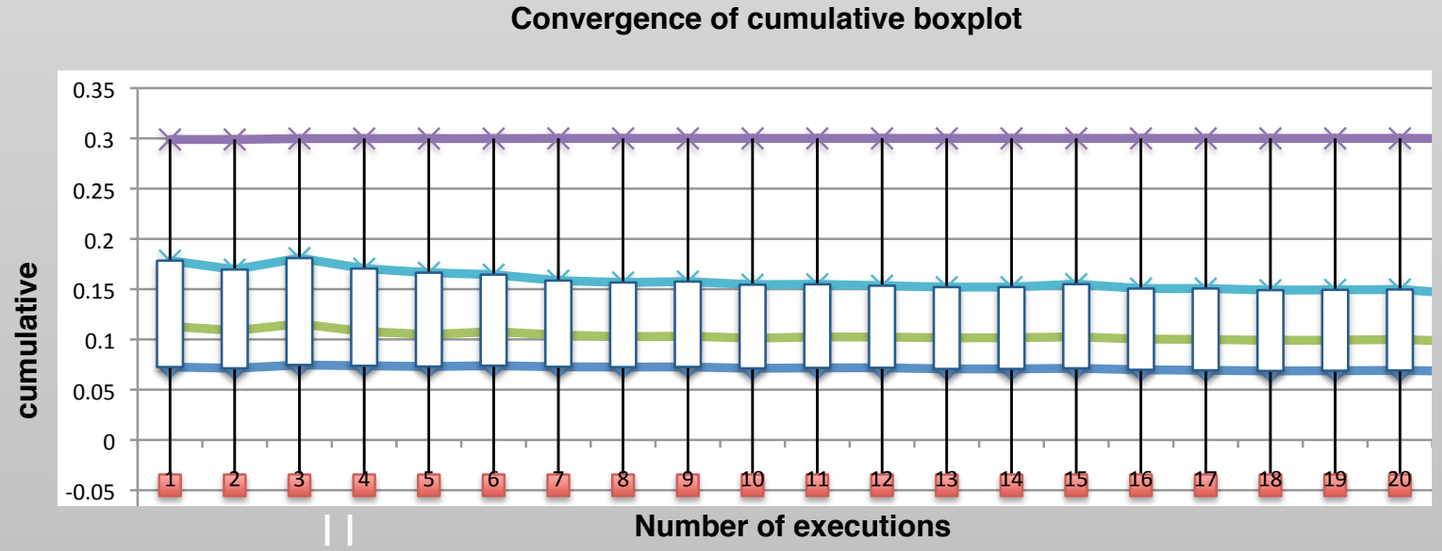


Cumulative box-plots of the distance of executions converge

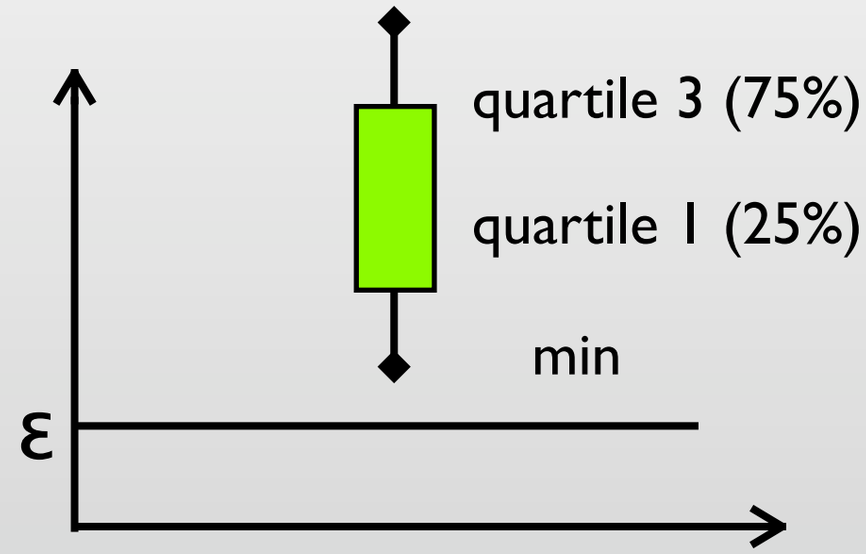




Fitness measurement

Fitness

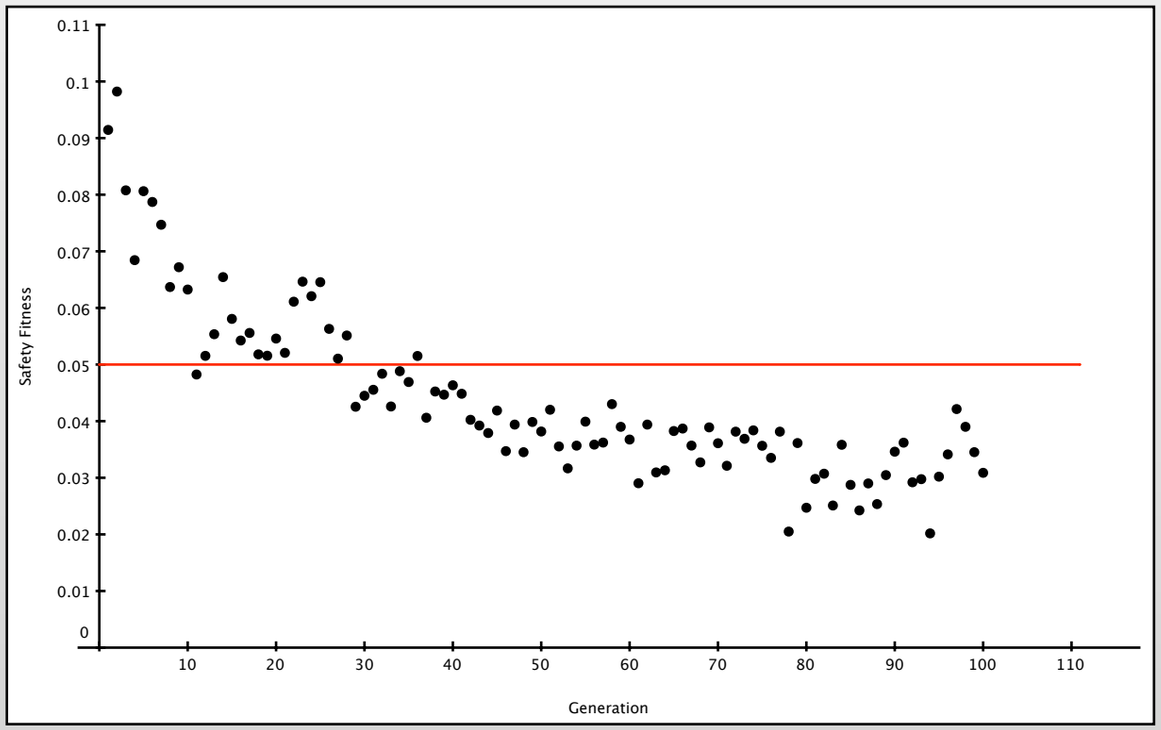
$$f = \begin{cases} min(D) + w_1 * quartile1(D) + w_3 * quartile3(D) \\ \qquad\qquad \text{if } min(D) > \varepsilon, \\ min(D) - \varepsilon \qquad \text{if } min(D) \leq \varepsilon, \\ +\infty \text{ if the agent cannot move and suspend safely.} \end{cases}$$



Search objective: *bringing the box down to the threshold ε ,i.e. leading the agent to hit obstacles*

Result & discussion

evolutionary testing



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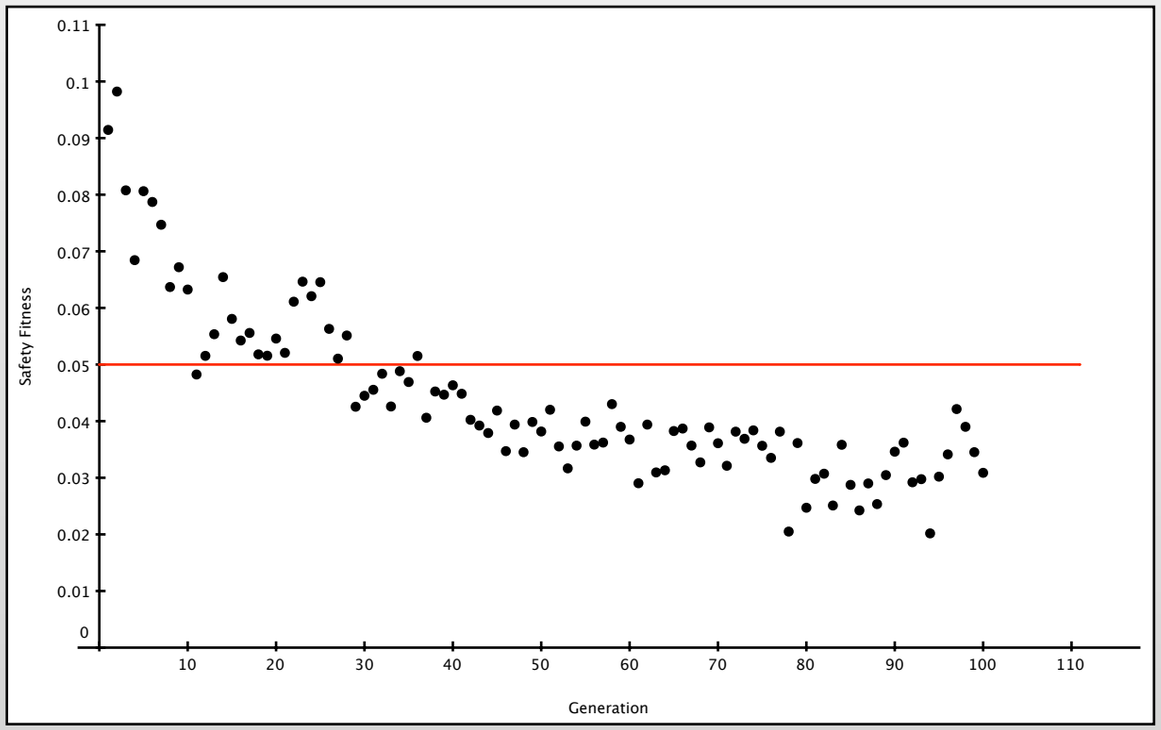

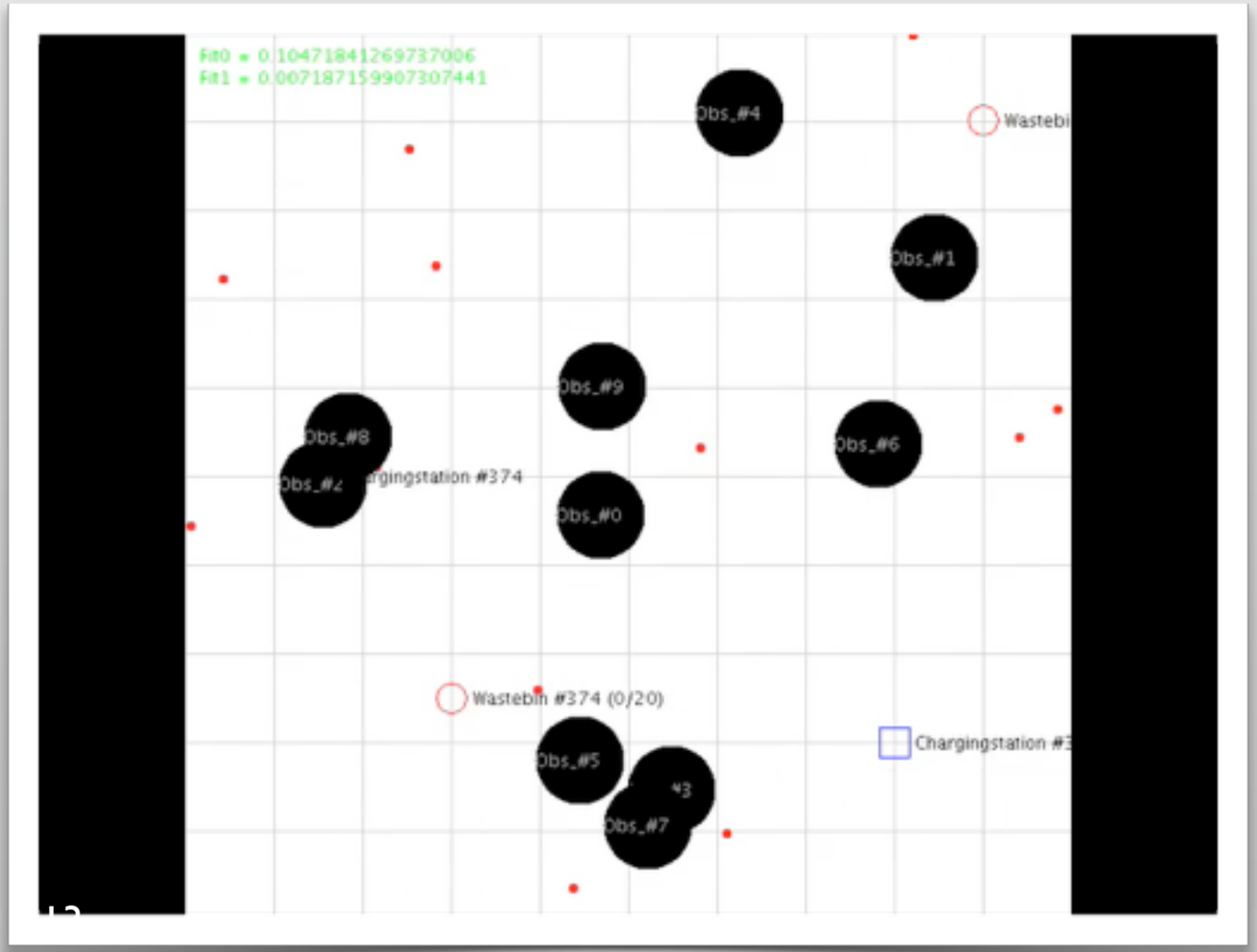

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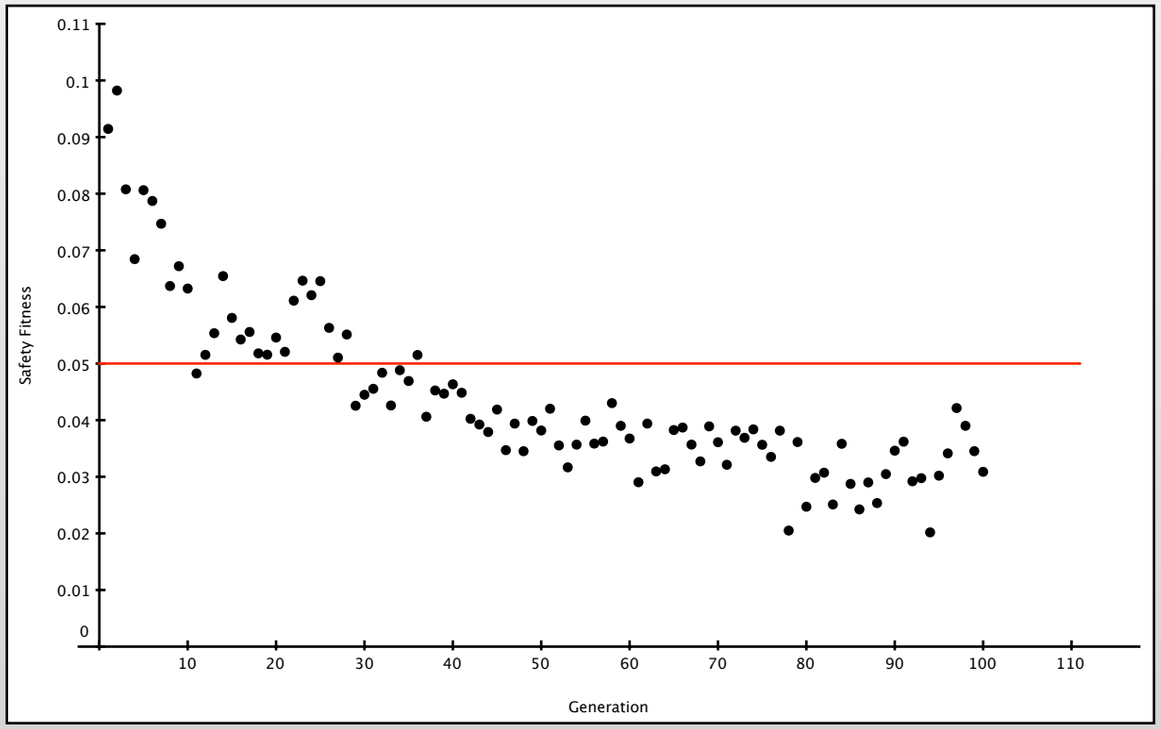
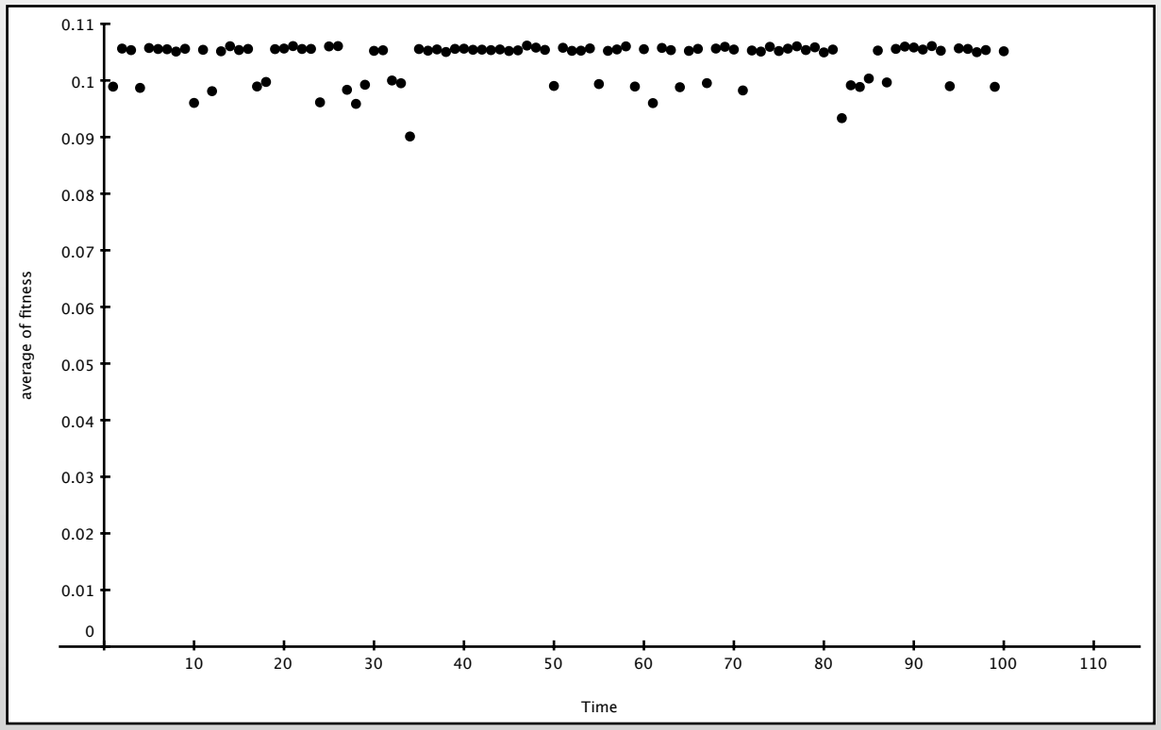


random testing



- evolutionary testing found better test cases than random testing
- and is more effective in detecting faults

Conclusion

- Autonomous agent testing is hard
  - Non-deterministic outputs
  - Variability of the world setting
- Evolutionary testing
  - Use quality requirements as evaluation criteria
  - Use them to guide the evolutionary generation of test input
  - Is more effective compared to random testing
  - Is cost-effective, requires almost no additional cost